



# The bisection method

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# Introduction

- In this topic, we will
  - Describe the idea behind the bisection method
  - Determine how fast it converges
    - We will compare it to Newton's method
  - Look at an example
  - Compare the algorithm with Newton's method
  - Look at an implementation

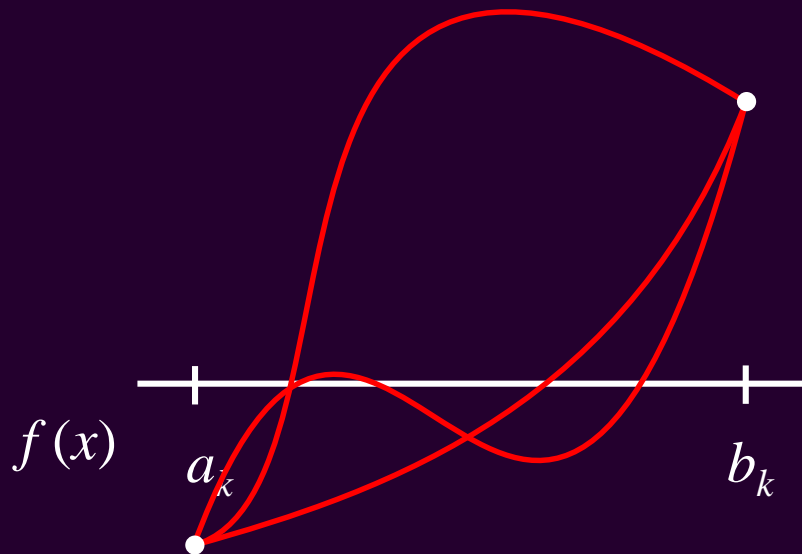






# Bracketing a root

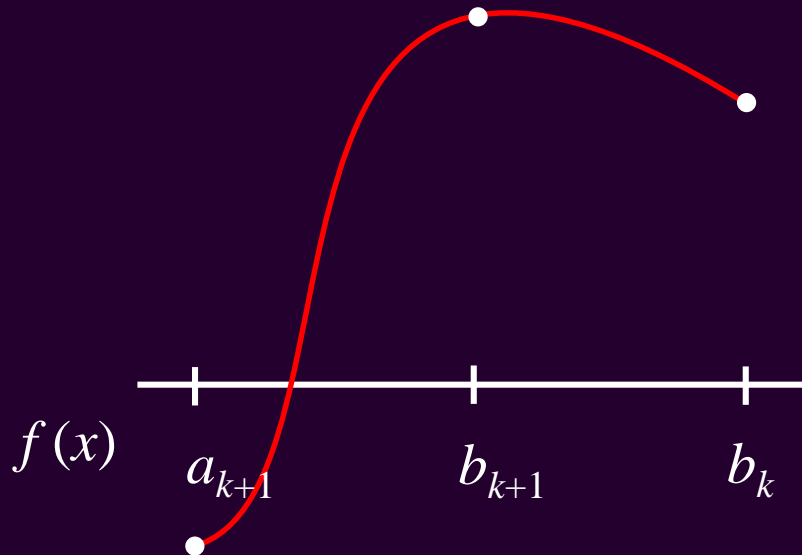
- Suppose we have a real-valued function of real variable and suppose that  $a_k$  and  $b_k$  are two points such that  $f(a_k)$  and  $f(b_k)$  have opposite signs
  - If  $f$  is continuous, the  $f$  must have a root on  $[a_k, b_k]$





# Bracketing a root

- Suppose we have a real-valued function of real variable and suppose that  $a_k$  and  $b_k$  are two points such that  $f(a_k)$  and  $f(b_k)$  have opposite signs
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# Calculating the mid-point

- Thus, given two bounds  $a_k$  and  $b_k$  such that  $f(a_k)$  and  $f(b_k)$  have opposite signs
  - Find the mid-point
$$m_k \leftarrow \frac{a_k + b_k}{2}$$
  - If  $f(m_k) = 0$ , we have found a root, so we are done
  - If  $f(a_k)$  and  $f(m_k)$  have opposite signs,  
let  $a_{k+1} \leftarrow a_k$  and  $b_{k+1} \leftarrow m_k$
  - Otherwise,  $f(m_k)$  and  $f(b_k)$  have opposite signs,  
let  $a_{k+1} \leftarrow m_k$  and  $b_{k+1} \leftarrow b_k$





# Error analysis

- Approximate the root by choosing whichever end-point has the smallest absolute value
  - What is the maximum error?
  - The root could be arbitrarily close to the other end-point, so the maximum error is  $h = b_k - a_k$
  - With each step, the maximum error is halved, or  $\frac{1}{2}h$ 
    - Thus, if  $h$  is the error, this technique is  $O(h)$





# Example

- Find the first root of  $2e^{-2x} - e^{-x}$  starting with  $[0, 1]$ 
  - The solution is  $\ln(2)$

$k$	$a_k$	$b_k$	$f(a_k)$	$f(b_k)$	Maximum error	$m_k$	$f(m_k)$
0	0	1	1.0	-0.09721	1	0.5	0.1292
1	0.5	1	0.1292	-0.09721	0.5	0.75	-0.02611
2	0.5	0.75	0.1292	-0.02611	0.25	0.625	0.03775
3	0.625	0.75	0.03775	-0.02611	0.125	0.6875	0.002848
4	0.6875	0.75	0.00285	-0.02611	0.0625	0.71875	-0.01232
5	0.6875	0.71875	0.00285	-0.01232	0.03125	0.703125	-0.004915
6	0.6875	0.703125	0.00285	-0.004915	0.015625	0.6953125	-0.001079
7	0.6875	0.6953125	0.00285	-0.001079	0.0078125	0.69140625	0.0008727
8	0.69140625	0.6953125	0.0008727	-0.001079	0.00390625	0.693359375	-0.0001061
9	0.69140625	0.693359375	0.0008727	-0.0001061	0.001953125	0.6923828125	0.0003826
10	0.6923828125	0.693359375	0.0003826	-0.0001061	0.0009765625		

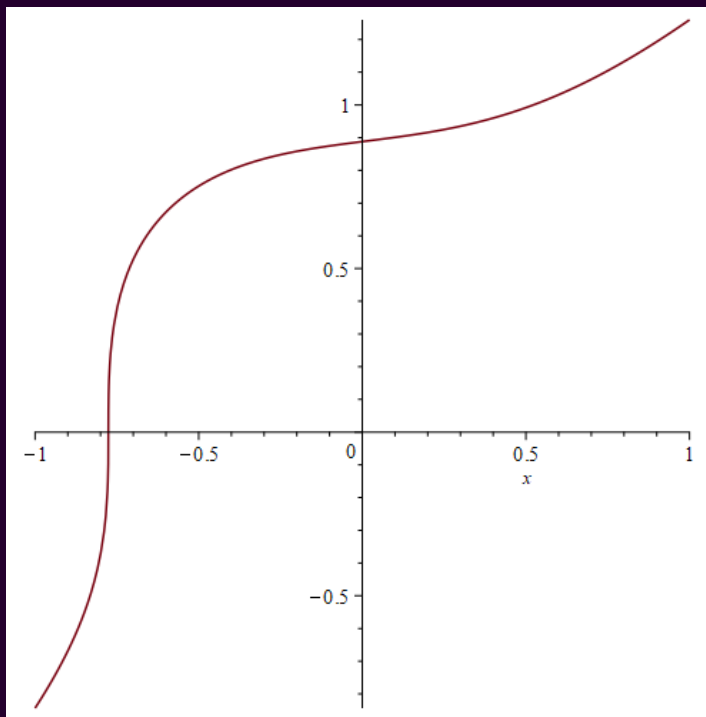




# Comparison with Newton's method

- The bisection method converges very slowly
  - However, if there is a root and if  $f$  is continuous on  $[a_0, b_0]$ , it is very likely to converge
  - It may not converge if the slope at the root is close to infinity
    - For example,

$$\sqrt[3]{x^3 + 0.3x + 0.7}$$







# Implementation

```
double bisection( std::function<double( double x )> f,
                 double a, double b,
                 double eps_step, double eps_abs,
                 unsigned int max_iterations ) {
    assert( a < b );

    double fa{ f( a ) };
    double fb{ f( b ) };

    if ( !std::isfinite( fa ) || !std::isfinite( fb ) ) {
        return NAN;
    }

    if ( fa == 0.0 ) {
        return a;
    }

    if ( fb == 0.0 ) {
        return b;
    }
}
```



C/C++ Code is provided to demonstrate the straight-forward nature of these algorithms and not required for the examination





# Implementation

```
for ( unsigned int k{0}; k < max_iterations; ++k ) {  
    double m{ a + (b - a)/2.0 };    // This avoids overflow  
    double fm{ f( m ) };  
  
    if ( !std::isfinite( fm ) ) {  
        return NAN;  
    }  
  
    if ( fm == 0.0 ) {  
        return m;  
    } else if ( std::signbit( fa ) == std::signbit( fm ) ) {  
        a = m;  
        fa = fm;  
    } else {  
        b = m;  
        fb = fm;  
    }  
}
```



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# Implementation

```
if ( ( b - a ) < eps_step ) {
    if ( std::abs( fa ) <= std::abs( fb ) ) {
        if ( std::abs( fa ) < eps_abs ) {
            return a;
        }
    } else {
        if ( std::abs( fb ) < eps_abs ) {
            return b;
        }
    }
}
     $b_{k+1} - a_{k+1} < \varepsilon_{\text{step}}$  and either
     $|f(a_{k+1})| < \varepsilon_{\text{abs}}$  or  $|f(b_{k+1})| < \varepsilon_{\text{abs}}$ ,
    returning whichever is smaller in absolute value

return NAN;
}
```



C/C++ Code is provided to demonstrate the straight-forward nature of these algorithms and not required for the examination





# Summary

- Following this topic, you now
  - Understand the idea behind the bisection method
  - Know that it converges according to  $O(h)$
  - Have seen an example
  - Understand that it will generally converge under normal conditions
  - Considered an implementation







# References

- [1] [https://en.wikipedia.org/wiki/Bisection\\_method](https://en.wikipedia.org/wiki/Bisection_method)





# Acknowledgments

None so far.





# Colophon

These slides were prepared using the Cambria typeface. Mathematical equations use Times New Roman, and source code is presented using Consolas. Mathematical equations are prepared in MathType by Design Science, Inc. Examples may be formulated and checked using Maple by Maplesoft, Inc.

The photographs of flowers and a monarch butter appearing on the title slide and accenting the top of each other slide were taken at the Royal Botanical Gardens in October of 2017 by Douglas Wilhelm Harder. Please see

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for more information.





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